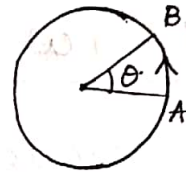


## CIRCULAR MOTION

When a particle moves along a curved path, the particle is said to undergo curvilinear motion. If the curve is an arc of a circle, the motion is called circular motion. i.e; Motion of a body along a circular path is known as circular motion. In this type of motion, the centre of rotation remains fixed. eg:- motion of a fan.

### Angular Displacement ( $\theta$ )

The displacement of a particle in circular motion is measured in terms of angular displacement  $\theta$ . It is the total angle (in radians) through which the particle has rotated. Unit is radians.



### Angular Velocity ( $\omega$ )

The rate of change of angular displacement is termed as angular velocity. If a body is rotating with uniform angular velocity ' $\omega$ ' and ' $\theta$ ' is the angular displacement in ' $t$ ' sec, then;

$$\omega = \theta/t;$$

Mathematically;  $\omega = \frac{d\theta}{dt}$

Unit is rad/sec.

Angular velocity can also be expressed in terms of revolutions per minute (rpm)

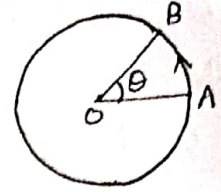
$$\text{i.e; } \omega = N \text{ rpm}$$

$$= \frac{2\pi N}{60} \text{ rad/sec}$$

$$1 \text{ rev} = 2\pi \text{ rad.}$$

## Relation between linear velocity & angular velocity:-

Consider the body moving in a circle as shown in Fig. The initial position of the body is at A and after time 't', the body is at B.



The  $\angle AOB = \theta$ .

Angular velocity:  $\omega = \theta/t$

Let  $v =$  linear velocity  $= \frac{\text{linear displacement}}{\text{time}}$

But linear displacement = arc AB =  $OA \times \theta$   
 $= r \times \theta$  ( $\because OA = \text{radius of circle} = r$ )

$$\therefore v = \frac{r \times \theta}{t} \quad (\because \theta/t = \omega)$$

$$\boxed{v = r\omega}$$

## Angular Acceleration ( $\alpha$ )

The rate of change of angular velocity is termed as angular acceleration. It may be uniform or variable.  
Unit is  $\text{rad/sec}^2$

$$\boxed{\alpha = \frac{d\omega}{dt}} = \frac{d}{dt} \left( \frac{d\theta}{dt} \right)$$

$$\boxed{\alpha = \frac{d^2\theta}{dt^2}}$$

$$\alpha = \frac{d\omega}{dt} \times \frac{d\theta}{d\omega} = \frac{d\theta}{dt} \times \frac{d\omega}{d\theta}$$

$$\therefore \boxed{\alpha = \omega \cdot \frac{d\omega}{d\theta}}$$

## Relation between linear acceleration & angular acceleration:

We have;  $v = r\omega$

Differentiating w.r.t 't'

$$\frac{dv}{dt} = \frac{d}{dt}(r\omega)$$

$$= r \frac{d\omega}{dt}$$

$$\therefore \boxed{a = r\alpha}$$

$$\left[ \begin{array}{l} \therefore a = \frac{dv}{dt} \\ \alpha = \frac{d\omega}{dt} \end{array} \right]$$

$\therefore$  linear acceleration is equal to  $r$  times angular acceleration.

## Motion of rotation under constant angular acceleration (Equations of circular motion)

Consider a particle moving in a circular path.

let  $\omega_0$  = initial angular velocity

$\omega$  = final angular velocity

$t$  = time taken by the particle to change its velocity from  $\omega_0$  to  $\omega$ .

$\alpha$  = angular acceleration

$\theta$  = angular displacement.

Angular acceleration =  $\frac{\text{change of angular velocity}}{\text{time}}$

$$\text{i.e., } \alpha = \frac{\omega - \omega_0}{t}$$

$$\alpha t = \omega - \omega_0$$

$$\therefore \boxed{\omega = \omega_0 + \alpha t} \longrightarrow \textcircled{1}$$

Angular displacement = Average angular velocity  $\times$  time

$$\theta = \left( \frac{\omega_0 + \omega}{2} \right) t$$

Substituting for  $\omega$  from (1)

$$\theta = \left( \frac{\omega_0 + \omega_0 + \alpha t}{2} \right) t = (\omega_0 + \frac{1}{2} \alpha t) t$$

$$\therefore \boxed{\theta = \omega_0 t + \frac{1}{2} \alpha t^2} \longrightarrow (2)$$

Angular displacement =  $\left( \frac{\omega_0 + \omega}{2} \right) t$

Substituting for  $t$  from (1)

$$\theta = \left( \frac{\omega_0 + \omega}{2} \right) \left( \frac{\omega - \omega_0}{\alpha} \right)$$

$$= \frac{\omega^2 - \omega_0^2}{2\alpha}$$

$$\therefore \boxed{\omega^2 = \omega_0^2 + 2\alpha\theta}$$

Comparison between linear motion & angular motion

Sl No.	Description	Linear motion	Angular motion
1.	Initial velocity	$u$	$\omega_0$
2.	Final velocity	$v$	$\omega$
3.	Acceleration	$a$	$\alpha$
4.	Displacement	$s$	$\theta$
5.	Formula for final velocity	$v = u + at$	$\omega = \omega_0 + \alpha t$
6.	Formula for distance travelled	$s = ut + \frac{1}{2} at^2$	$\theta = \omega_0 t + \frac{1}{2} \alpha t^2$
7.	Formula for final velocity	$v^2 = u^2 + 2as$	$\omega^2 = \omega_0^2 + 2\alpha\theta$
8.	Differential formula for velocity	$v = \frac{ds}{dt}$	$\omega = \frac{d\theta}{dt}$
9.	Differential formula for acceleration	$a = \frac{dv}{dt} = v \cdot \frac{dv}{ds}$	$\alpha = \frac{d\omega}{dt} = \omega \cdot \frac{d\omega}{d\theta}$